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(71)Name of Applicant :  
 1)Dr.Radhika Dora  
 Address of Applicant :Professor, Department of EEE  
 Geethanjali College of Engineering and Technology, Cheeryal  
 Village, KeesaraMandal, Hyderabad, Telangana- 501301  
 Telangana India  
 2)Duvvuru. Saritha  
 3)Dr. Ananda babu J  
 4)Suhas K C  
 5)Anitha K  
 6)Dr. D.S.Naga Malleswara Rao  
 7)Dr.Idamakanti Kasireddy  
 8)Dr.Addanki Purna Ramesh  
 9)Suman Tenali  
 10)Kesava Vamsi Krishna K V  
 11)Dr.Anand J Dhas  
 (72)Name of Inventor :  
 1)Dr.Radhika Dora  
 2)Duvvuru. Saritha  
 3)Dr. Ananda babu J  
 4)Suhas K C  
 5)Anitha K  
 6)Dr. D.S.Naga Malleswara Rao  
 7)Dr.Idamakanti Kasireddy  
 8)Dr.Addanki Purna Ramesh  
 9)Suman Tenali  
 10)Kesava Vamsi Krishna K V  
 11)Dr.Anand J Dhas

(57) Abstract :  
 Abstract An electric smart bike is portrayed and incorporates a voice recognition sense air speed at the bike, an electric engine to give intention power to the bike, and a regulator operatively associated with the engine, the regulator to control the electric engine utilizing the speed sensed by the air speed sensor. The regulator incorporates a set electric-engine boundary for the yield intensity of the engine. The electric-engine boundary can be bike speed. The regulator can likewise utilize ground tendency to decide the ability to be yield by the engine to help with driving the bicycle. A smart bike technique for deciding a client movement incorporate or characterize a majority of pattern marks, every standard mark relating to a sort of client action and having information shaped from a first information speaking to a differing static electric field and a subsequent information speaking to movement. Information receptive to a changing static electric field is gotten from a first sensor, and information receptive to movement is acquired from a subsequent sensor. The primary information is joined with the subsequent information, and the client action is distinguished dependent on a correlation of the consolidated first and second information with the majority of pattern marks. The regulator can utilize ground tendency to decide the ability to be yield by the engine to charge a battery in the bicycle. The regulator can set the intensity of engine help to be more prominent in a more noteworthy headwind than in a lighter headwind. The regulator utilizes rider weight and rider stature as boundaries for controlling the engine.

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